

LEGRAND - BP30076

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Cat. N°: 4 149 40





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1. DESCRIPTION - USE

- . Module dedicated to Energy Management System (EMS CX3) use.
- . It performs conversion from the EMS $\mathrm{CX^3}$ bus to Modbus RS485 protocol.

Symbol:



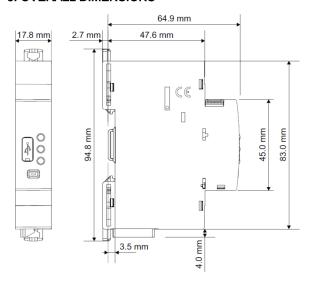
2. RANGE

. Cat. n° 4 149 40: EMS CX3/Modbus RS485 Interface

Width:

. 1 module. 17,8 mm width.

3. OVERALL DIMENSIONS



4. PREPARATION -CONNECTION

Fixing:

. On symmetric rail EN/IEC 60715 or DIN 35 rail

Operating positions:

. Vertical, Horizontal, Upside down, On the side

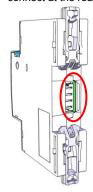
Power Supply:

- . Mandatory in 12 VDC via the specific Power supply module Cat $n^{\circ}4$ 149 45
- . Two ways:

via specific communication patch cords (cat. nos 4 149 07/08/09) to connect at the downstream through dedicated ports



via specific communication rails (cat. nos 4 149 01/02/03) to connect at the rear through dedicated connectors.



4. PREPARATION -CONNECTION (continued)

Recommended tools:

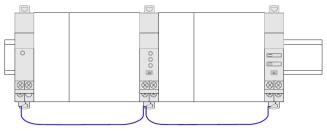
. For fixing: flat screwdriver 5.5 mm (6 mm maximum).

Data connection (EMS CX³ modules inter-connection):

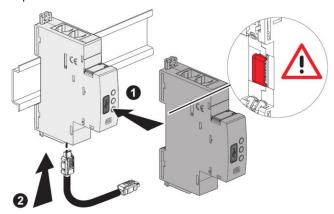
. Via specific communication patch cords (cat. nos 4 149 07/08/09)



Allow data transmission between the different EMS CX3 modules. This type of connection is recommended when there are few EMS CX3 modules, distributed all over the enclosure.



Implementing: with this configuration, the plastic protection cover of the backside communication ports on the EMS CX3 module must be keep on.



4. PREPARATION -CONNECTION (continued)

Data connection (EMS CX³ modules inter-connection) (continued):

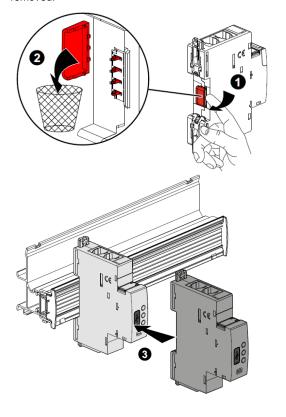
. Via specific communication rails (cat. nos 4 149 01/02/03).



. Allow data transmission between the different EMS $\mbox{CX}^{\mbox{\tiny 3}}$ modules. This type of connection is recommended when there are several EMS CX3 modules on the same DIN row.



Implementing: with this configuration, the plastic protection cover of the backside communication ports on the EMS CX3 module must be



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4. PREPARATION -CONNECTION (continued)

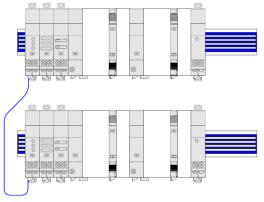
Data connection (EMS CX³ modules inter-connection)

(continued):

. Via a mix between specific communication patch cords and communication rails in order to create a link between several rows

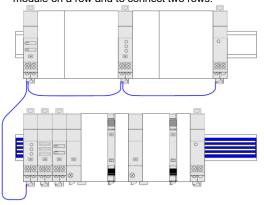
- Individually connected with communication rails.

The communication patch cord allows to connect two rows.



Individually connected with communication patch cords & communication rail.

The communication patch cords allow to connect EMS CX³ module on a row and to connect two rows.



Front USB port:

. Allows, if needed (e.g. for configuration), to connect the EMS CX³ Modbus/EMS Interface to a computer via a "type B" micro USB/USB commercial cable.



. Via the Legrand - EMS configurator software (download for free) is possible to:

test an EMS installation

update the module's firmware

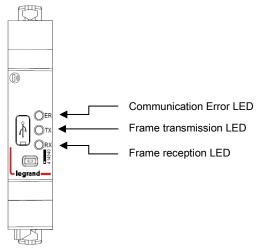
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..create a link between two modules with Link Functionality configure the modules characteristics if the lateral DIP Switches remain on 0000 position (for the modules 4 149 30/32) make the extended addressing procedure (see § 6.2.2)

5. GENERAL CHARACTERISTICS

Front face marking:

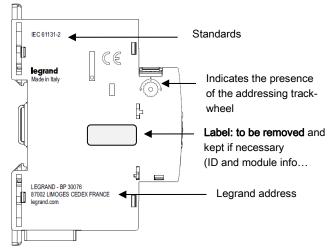
. By permanent ink pad printing (red line) and laser marking



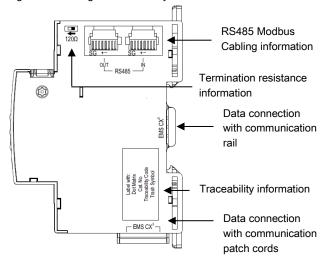
Lateral side marking:

. By laser.

left side: Standard and programming information



right side: cabling and traceability information

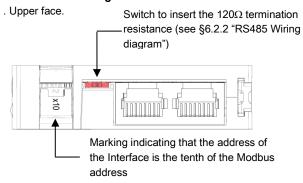


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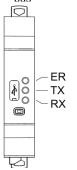
5. GENERAL CHARACTERISTICS (continued)

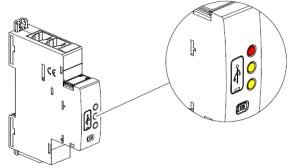
Lateral side marking:



Signalling LEDs:

- . Interface is equipped with 3 signalling LEDs:
- "ER": Communication error led \rightarrow it blinks red if there is an error on the communicating bus
- "TX" and "RX": frame transmission and reception signalling led → they blink yellow when there is communication activity on the bus

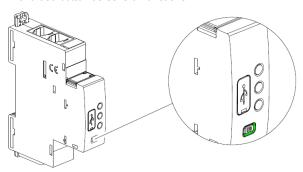




Multi-Functions button:

. Front face button as several functions:

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5. GENERAL CHARACTERISTICS (continued)

Multi-Functions button (continued):

. Gives information about the operating state on the module Possible states:

Led colour	State	Meaning	
red	Slow blinking	Error (e.g. addressing error)	
	Fast blinking	No function	
	Steady (without pressing the multifunction button)	System alarm detected (see Note*)	
	Steady (pressing the multifunction button longer than 20 sec.)	Total reset [any firmware updates are preserved]	
green	Slow blinking	System process is running. Wait until the Led turns steady	
	Fast blinking (pressing the multifunction button for 10 sec.)	put in "Stand-by" the EMS CX³ module (no remote action and communication available)	
	Steady	System OK, connection is running	
orange	Slow blinking	Creation of a link with "Link Functionality" procedure (see next §)	
	Fast blinking	Device's firmware update in progress	
	Steady	No function	

* Note

. Possible system alarms detected by the Modbus/EMS Interface:

loss of communication with an EMS module error in addressing procedure: possible mix between local and remote address (see § 6)

duplicate function error: two EMS modules with the same function have the same address.

. To turn off the system alarm:

solve the problem according to the indication of the alarm push the Multifunction button on the Interface \rightarrow the led become steady green

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5. GENERAL CHARACTERISTICS (continued)

Link Functionality:

. This function allows you to link two EMS CX^3 modules to create automatic actions that, once programmed, can run independently without a connection to a manager is needed.

The basic rule is the link between an event (circuit breaker that trip, a threshold exceeded, etc.) and an action accordingly (signalling, opening of a circuit by motorized control or contactor, etc.).

Possible associations are:

	Action module		
Event generator	Command: 4 149 32	State + Command: 4 149 31	State: 4 149 30
Measure: 4 149 19/20/23	√	√	Only with the module configured (locally or remotely) as shown:
State: 4 149 29/30	√	√	Is sufficient to configure the module (locally or remotely) as "Slave"
State + Command: 4 149 31	√	√	Is sufficient to configure the module (locally or remotely) as "Slave"

Note:

- association can only be of type 1 to 1 (1 event and 1 action).

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- modules already associated cannot be used for other associations.
- all the configuring procedure will be done with the Configuration Software (available online for free). [For more details refer to the Installation Manual of EMS CX3 Configuration software]

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Modules compatible with "Link Functionality" feature: firmware versions and production date:

Cat n°	Firmware version	Production date indicated on the label sticked on the side of the module
4 149 19	ver. ≥ 2.0.1	date ≥ 18W29
4 149 20	ver. ≥ 2.0.1	date ≥ 18W49
4 149 23	ver. ≥ 2.0.1	date ≥ 18W49
4 149 29	ver. ≥ 2.0.1	date ≥ 18W49
4 149 30	ver. ≥ 2.0.2	date ≥ 18W32
4 149 31	ver. ≥ 2.0.6	date ≥ 18W45
4 149 32	ver. ≥ 3.0.2	date ≥ 18W39
4 149 36	ver. ≥ 2.0.4	date ≥ 18W38
4 149 37	ver. ≥ 2.0.4	date ≥ 18W43
4 149 40	ver. ≥ 3.0.8	date ≥ 18W34

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5. GENERAL CHARACTERISTICS (continued)

RS485 communication port's characteristics:

- . Programmable addresses: from 1 to 247
- . Galvanically isolated respect to auxiliary supply
- . Standard RS485 3 wires, half-duplex (+, -, Signal ground); for the RJ45 connector, pin 4 (-), pin 5 (+) and pin 8 (SG)
- . Protocol Modbus® RTU
- . EMS CX³/RS485 interface automatically detects the Modbus parameters of other devices in the system and automatically sets its Modbus parameters.
- . Possible values:

Baud rate: 1,2 - 2,4 - 4,8 - 9,6 - 19,2 - 38,4 - 57,6 - 115,2 kbps

Parity bit: none, even, odd

Stop bit: 1 or 2

Insulation voltage:

. Ui = 400 V

Pollution degree:

. 2 according to IEC/EN 60898-1.

Overvoltage category:

- 111

Dielectric strength:

. 2500 V

Plastic material:

- . Self-extinguishing polycarbonate.
- . Heat and fire resistant according to IEC/EN 60695-2-12, glow-wire test at 960 $^{\circ}\text{C}$.
- . Classification UL 94 / IECEN 60695-11-10: V1

Ambient operating temperature:

. Min. = -25°C. Max. = +70°C

Ambient storage temperature:

. Min. = -40°C. Max. = +70°C

Protection Index:

- . Protection index of terminals against direct contacts: IP2X (IEC/EN 60529).
- . Protection index of terminals against solid and liquid bodies (wired device): IP 20 (IEC/EN 60529).
- . Protection index of the front face against solid and liquid bodies: IP 40 (IEC/EN 60529).
- . Class II, front panel with faceplate.

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Average weight per device:

. 0,050 kg.

Volume when packed:

. 0,21 dm³.

Consumption:

. Values at 12 VDC

Configuration	W	mA
Stand-by	0,316	26,3
Communication	0,344	28,7

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6. SYSTEM ARCHITECTURES

The EMS CX³ is a polyvalent system and, according to the needs of the customer, can be set up and/or used as "Stand-alone" or "Supervised" system. Based on this choice the configuration and addressing methods are different.

Four possible architectures are provided:

- 6.1 Stand-alone system
 - 6.1.1 with local addressing (through the track wheel)
 - 6.1.2 with remote addressing (through a computer)
- 6.2 Supervised (Computer Supervisory System)

dedicated to this module for details).

- 6.2.1 with local addressing
- 6.2.2 with remote addressing

6.1 Stand-alone system

. **Stand-alone** = autonomous system. To be used by the end-user if it is not necessary to have a computer for the supervision outside the envelope. Everything can be managed on site.

6.1.1 Stand-alone system with local addressing (through the track wheel)

Local addressing advantages:

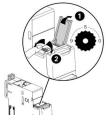
- No configuration software needed to set-up the installation
- **It is not necessary to use a computer to manage settings** (configurations, test, ...) and to use the system (visualize and be alerted, ...). Everything can be done through the Mini configuration module (local display, cat. no 4 149 36/37). [Refer to the technical sheet
- No communication Interfaces or gateways are required.
- Installation can be done without the intervention of a System Integrator

Programming procedure:

. For EMS CX3 modules which need some: mandatory through to lateral DIP-switch of each EMS CX3 modules (see § "Module configuration")

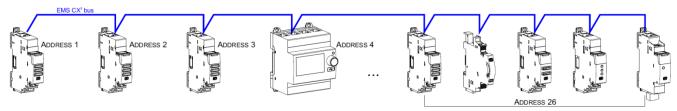
Addressing procedure:

- . For all EMS CX³ modules: mandatory through the track wheel located on the top upper face of each EMS CX³ modules
- . Marked from 0 to 9 in order to locally define the Modbus address of the EMS CX3 modules



Consequences of the local addressing mode (through the track wheel):

- . Each device of the system must be addressed.
- . Addresses available: from 1 to 9
- . Address 0 not permitted
- . It is possible to assign to several devices the same address with the purpose of grouping different functions, because they are related to the same electrical circuit. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ mini configuration module (local display) the grouped function will be displayed as a unique "device" with all grouped functions. [Refer to the schemes hereunder]



Note for the mini configuration module (local display)

- . It is possible to assign it the same address as another EMS CX3 through the programming menu of the device
- . The mini configuration module can be placed everywhere in the EMS CX3 bus

6. SYSTEM ARCHITECTURES

6.1 Stand-alone system (continued)

6.1.2 Stand-alone system with remote addressing (through a computer)

Remote addressing advantages:

- Whole configuration (addresses and functions) can be set up through the EMS Configuration software
- Configuration software available for free
- Automatic detection of the EMS CX3 modules installed in the system (characteristics, functions, configuration...)
- Increased settings possibilities: load shedding function
- Increased addressing: up to 30 Modbus addresses in a system

Programming procedure:

. For EMS CX³ modules which need some: possible through the lateral DIP-switch of each EMS CX³ modules (see § "Module configuration").

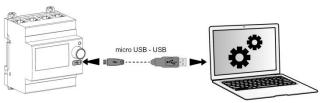
Addressing procedure:

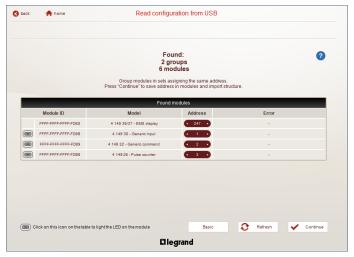


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- . It is not necessary to address the EMS CX3 modules. The track wheel must be left in default position "0".
- . All the addressing/configuring procedure will be done with the Configuration Software (available online for free)
- . With remote addressing, the software does the automatic detection of modules installed in the system, but the supervision is not possible until the user assigns the remote address and all the characteristics to each module.

Note: it is mandatory to connect the computer to the mini configuration module with an USB-micro USB cable. [For more details, refer to User Manual Document]





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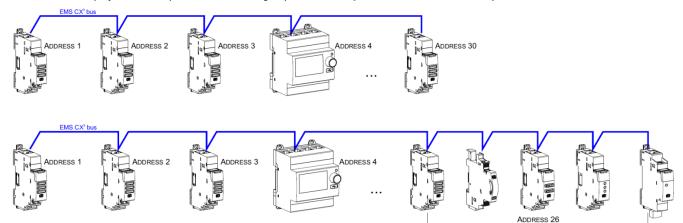
6. SYSTEM ARCHITECTURES

- 6.1 Stand-alone system (continued)
 - 6.1.2 Stand-alone system with remote addressing (through a computer) (continued)

Consequences for the system architecture:

- for 1 mini configuration module (cat. no 4 149 36/67)
 - up to 30 EMS CX³ modules (e.g. 30 devices grouped per functions with addresses from 1 to 30)

It is possible to assign to several devices the same address with the purpose of grouping different functions, because they are related to the same electrical circuit. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ display or in a supervision system the grouped function will be displayed as a unique "device" with all grouped functions. [Refer to the schemes here under]



Note for the mini configuration module (local display)

- . It is possible to assign it the same address as another EMS CX3
- . The mini configuration module can be placed everywhere in the EMS CX3 bus

6.2 Supervised system (Computer Supervisory System)

. **Supervised system** = System to be used through a Computer Supervisory System to remotely read data from the EMS CX³ devices and/or do operations on these devices (e.g. commands of a motor driven or contactor ...).

6.2.1 Supervised system-with local addressing (through the track wheel)

Local addressing advantages:

- No configuration software needed to set-up the installation
- Installation can be done without the intervention of a System Integrator

Programming procedure:

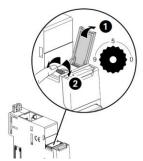
. For EMS CX3 modules which need some: mandatory through to lateral DIP-switch of each EMS CX3 modules (see § "Module configuration")

Addressing procedure:

- . For all EMS CX3 modules: mandatory through the track wheel located on the top upper face of each EMS CX3 modules
- . Marked from 0 to 9 in order to locally define the Modbus address to EMS CX3 modules

In this system the Modbus address of an EMS CX^3 module device or group of modules (several functions) is obtained considering the address of the interface Modbus/EMS CX^3 Interface as tenth and the address of a device or group of function as unit (e.g. Interface address 1 = 10 \rightarrow address of module n^5 = Modbus address 15)

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6. SYSTEM ARCHITECTURES (continued)

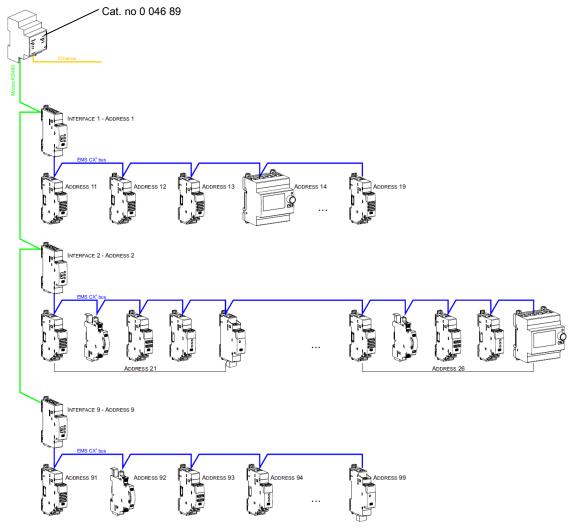
- 6.2 Supervised system (Computer Supervisory System) (continued)
 - 6.2.1 Supervised system-with local addressing (through the track wheel) (continued)

Consequences of the local addressing mode (through the track wheel):

- . Each device of the system must be addressed.
- . Addresses available: from 1 to 9
- . Address 0 not permitted

It is possible to assign to several devices the same address with the purpose of grouping different functions, because they are related to the same electrical circuit. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ display or in a supervision system the grouped function will be displayed as a unique "device" with all grouped functions. [Refer to the scheme hereunder]

Note: In this configuration the Modbus address of an EMS CX 3 module device or group of modules (several functions) is obtained considering the address of the interface Modbus/EMS CX 3 Interface as tenth and the address of a device or group of function as unit (e.g. Interface address 1 = 10 and device address = 5 \rightarrow Modbus address = 15)



Consequences for the system architecture:

- for 1 IP/Modbus gateway (cat. no 0 046 89):
 - o up to 81 Modbus address
 - mandatory limit of max. 9 Modbus/EMS CX³ interfaces or max. 1000 m of Modbus cable (cable Belden 9842, Belden 3106A or equivalent).
- for 1 Modbus/EMS CX3 Interface (cat. no 4 149 40):
 - o up to 30 EMS CX3 modules (ex. 30 devices grouped per functions with addresses from1 to 9)

Note: with local addressing, the Modbus/EMS CX³ interface, does the automatic detection of modules (characteristics, functions, configuration...)

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6. SYSTEM ARCHITECTURES (continued)

6.2 Supervised system (Computer Supervisory System) (continued)

6.2.2 Supervised system-with remote addressing (through a computer)

Remote addressing advantages:

- Whole of configuration (addresses and functions) can be done a remotely through the EMS Configuration software
- Configuration software available for free
- Automatic detection of the EMS CX3 modules installed in the system (characteristics, functions, configuration...)
- Increased settings possibilities: load shedding function
- Increased addressing: up to 32 Modbus/EMS CX3 interfaces
- Increased addressing: up to 247 Modbus addresses in a system

Programming procedure:

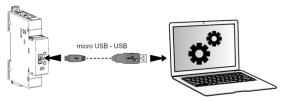
. For EMS CX³ modules which need some : possible through the lateral DIP-switch of each EMS CX³ modules (see § "Module configuration"). **Note:** via the configuration software it is possible to assign all the functions and characteristics of each EMS CX³ module

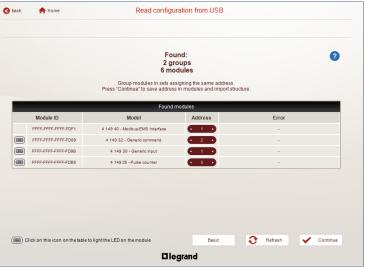
Addressing procedure:



- . It is not necessary to address the EMS CX3 modules. The track wheel must be left in default position "0".
- . All the addressing/configuring procedure will be done with the Configuration Software (available online for free)
- . With remote addressing, the software does the automatic detection of modules installed in the system, but the supervision is not possible until the user assigns the remote address and all the characteristics to each module.

Note: it is mandatory to connect the computer to the different Modbus/EMS CX³ interface with an USB-micro USB cable (one interface at a time). [For more details, refer to the User Manual Document]

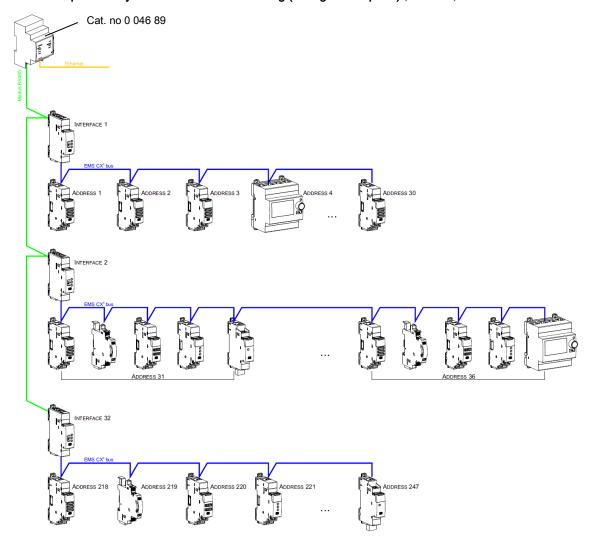




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6. SYSTEM ARCHITECTURES (continued)

- 6.2 Supervised system (Computer Supervisory System) (continued)
 - 6.2.2 Supervised system-with remote addressing (through a computer) (continued)



Consequences for the system architecture:

- for 1 IP/Modbus gateway (cat. no 0 046 89):
 - o up to 247 Modbus address
 - Because of Modbus: mandatory limit of max. 32 Modbus/EMS CX³ interfaces or max. 1000 m of Modbus cable (cable Belden 9842, Belden 3106A or equivalent).
- for1 Modbus/EMS CX3 Interface (cat. no 4 149 40):
 - o up to 30 EMS CX3 modules or grouped modules (e.g. 30 devices grouped per functions with addresses from 1 to 30)

It is possible to assign to several devices the same address with the purpose of grouping different functions, because they are related to the same electrical circuit. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ display or in a supervision system the grouped function will be displayed as a unique "device" with all grouped functions. [Refer to the scheme up here]

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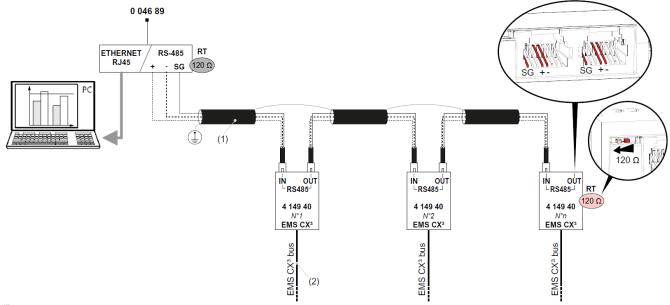
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6. SYSTEM ARCHITECTURES (continued)

6.2 Supervised system (continued)

6.2.2 Supervised system with remote addressing (continued)

RS485 Wiring diagram:



⁽¹⁾ BELDEN 9842, BELDEN 3106A (or equivalent) max. 1000 m Cat. 6 (FTP/UTP) max. 50 m

Note: it is not necessary to dedicate a RS485 / IP gateway for the EMS CX3 system. It is possible to mix several RS485 devices.

7. COMPLIANCE AND APPROVALS

Compliance to standards:

- . Compliance with Directive on electromagnetic compatibility (EMC) n° 2014/30/EU
- . Compliance with low voltage directive $n^{\circ}\ 2014/35/EU.$
- . Electromagnetic Compatibility:

IEC/EN 61131-2

Environment respect - Compliance with EU directives:

- . Compliance with Directive 2011/65/EU as amended by Directive 2015/863 (RoHS 2) on the restriction of the use of certain hazardous substances in electrical and electronic equipment.
- . Compliance with REACH regulation (1907/2006): at the date of the publication of this document no element of the SVHC substance list (updated on 27/06/2018) is present in these products.
- . WEEE directive (2012/19/EU): the sale of this product is subject to a contribution to eco-organisations in each country responsible for managing end-of-life products in the field of application of the European Waste Electronic and Electrical Equipment Directive.

Plastic materials:

- . Halogens-free plastic materials.
- . Marking of parts according to ISO 11469 and ISO 1043.

Packaging:

. Design and manufacture of packaging compliant to decree 98-638 of the 20/07/98 and also to directive 94/62/CE.

Environmental profile:

. PEP document available

Installation software:

. XL PRO³.



^{(2) 4 149 01/02/03 - 4 149 07/08/09}