

EMS CX³ - Signalling Auxiliary Contact (CA + SD)

Cat. N°: 4 149 29



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1. DESCRIPTION - USE

- . Module dedicated to Energy Management System (EMS CX³) use.
- . Auxiliary and Fault signalling electronic module (CA+SD): indicates contacts position (open or closed) and fault tripping of Legrand modular associated device (MCB, RCBO, RCCB or Remote trip head IS).

Symbol:



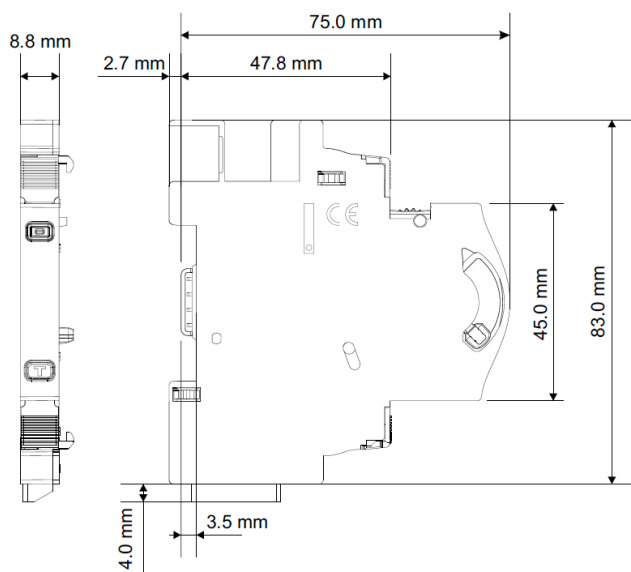
2. RANGE

- . Cat. n° 4 149 29: electronic auxiliary contact (CA) + fault signalling (SD).

Width:

- . ½ module. 8,8 mm width.

3. OVERALL DIMENSIONS



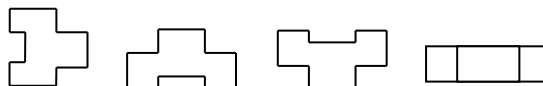
4. PREPARATION -CONNECTION

Fixing:

- . On symmetric rail EN/IEC 60715 or DIN 35 rail

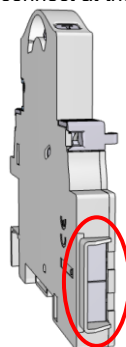
Operating positions:

- . Vertical, Horizontal, Upside down, On the side

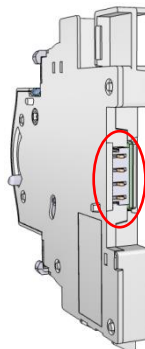


Power Supply:

- . Mandatory in 12 VDC via the specific Power supply module Cat n° 4 149 45
- . Two ways:
via specific communication patch cords (cat. nos 4 149 07/08/09) to connect at the downstream through dedicated ports



- via specific communication rails (cat. nos 4 149 01/02/03) to connect at the rear through dedicated connectors.



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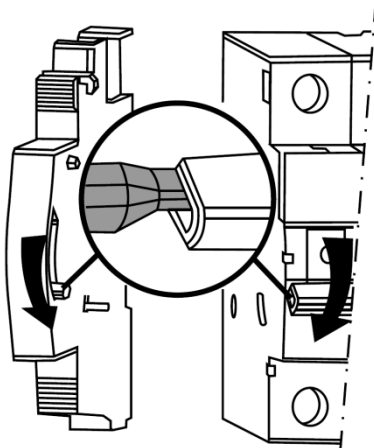
4. PREPARATION –CONNECTION (continued)

Manual action of the CA + SD:

- By the handle of the associated device.

Assembling:

- On the left side of Legrand MCB, IS, RCBO or RCCB
- No tools are required. Clipped by mean of plastic clamps on the associated device.
- Assembling products in OFF position
- The switching device of signalling auxiliaries must fit into the housing of the handle of the associated device.



List of allowed associations (General rules):

Three auxiliaries maximum which:

- two signalling auxiliaries
(Cat. nos 4 062 50/52/56/58/60/62/64/66, 4 149 29).
- only one control auxiliary
(Cat. nos 4 062 76/78/80/82/84/86/87).

- If signalling and control auxiliaries are associated on the same circuit breaker, the control auxiliary must be placed to the left of the signal auxiliary (ref. 4 062 5x / 6x or 4 149 29).

List of allowed associations (Particular rules):

With MCB's 1,5 modules per pole width:

- **if a remote tripping auxiliary** (Cat. nos 4 062 76/78/80/82/84/86/87) **is already mounted** on this kind of device, only 1 module width signalling auxiliaries (Cat. nos. 4 062 64/66) can be added. In this set up the ½ module signalling auxiliaries will not operate. Nothing changes for the other modular references.

With an isolating switch DX³-IS:

- only one signalling auxiliary CA type (Cat. nos 4 062 50/56/58/62/64/66) or CA+SD (Cat. n° 4 149 29).

With a remote trip head isolating switch DX³-IS, three auxiliaries maximum which:

- one or two signalling auxiliaries CA type Cat. nos 4 062 50/56/58/62/64/66) or CA+SD (Cat. n° 4 149 29).
- one control auxiliary (Cat nos 4 062 4 062 76/78/80/82/84/86/87).

4. PREPARATION –CONNECTION (continued)

Combination tables of the auxiliaries:

For devices 1 module per pole width:

		4 062 .. 50 / 52 / 56 / 58 / 60 / 62 / 64 / 66 / 76 / 78 / 80 / 82 / 84 / 86 / 87 4 149 29
	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 / 76 / 78 / 80 / 82 / 84 / 86 / 87 4 149 29	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 4 149 29
	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 / 64 / 66 / 76 / 78 / 80 / 82 / 84 / 86 / 87 4 149 29	4 062 .. 64 / 66
4 062 .. 76 / 78 / 80 / 82 / 84 / 86 / 87	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 4 149 29	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 4 149 29
	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 / 64 / 66 4 149 29	4 062 .. 64 / 66

For devices 1,5 modules per pole width:

		4 062 .. 50 / 52 / 56 / 58 / 60 / 62 / 64 / 66 / 76 / 78 / 80 / 82 / 84 / 86 / 87 4 149 29
	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 4 149 29	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 4 149 29
	4 062 .. 50 / 52 / 56 / 58 / 60 / 62 / 64 / 66 / 76 / 78 / 80 / 82 / 84 / 86 / 87 4 149 29	4 062 .. 64 / 66
4 062 .. 76 / 78 / 80 / 82 / 84 / 86 / 87	4 062 .. 64 / 66	4 062 .. 64 / 66

EMS CX³ - Signalling Auxiliary Contact (CA + SD)

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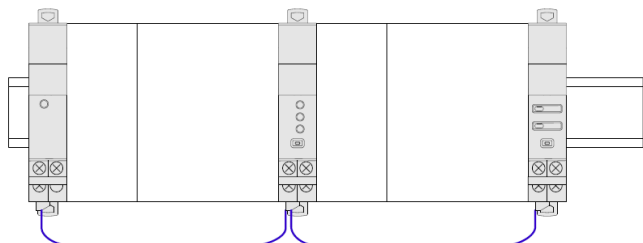
4. PREPARATION –CONNECTION *(continued)*

Data connection (EMS CX³ modules inter-connection):

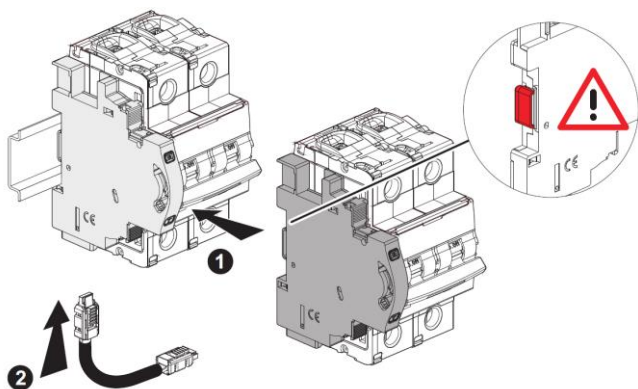
. Via specific communication patch cords (cat. nos 4 149 07/08/09)



Allow data transmission between the different EMS CX³ modules.
This type of connection is recommended when there are few EMS CX³ modules, distributed all over the enclosure.



Implementing: with this configuration, the plastic protection cover of the backside communication ports on the EMS CX³ module must be kept on.

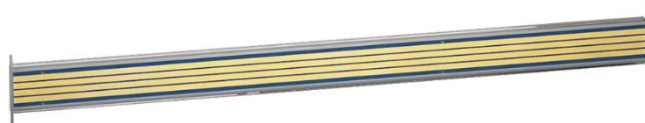


4. PREPARATION –CONNECTION *(continued)*

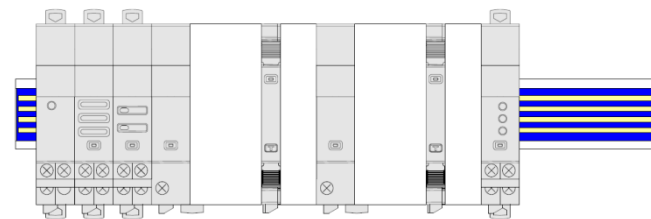
Data connection (EMS CX³ modules inter-connection)

(continued):

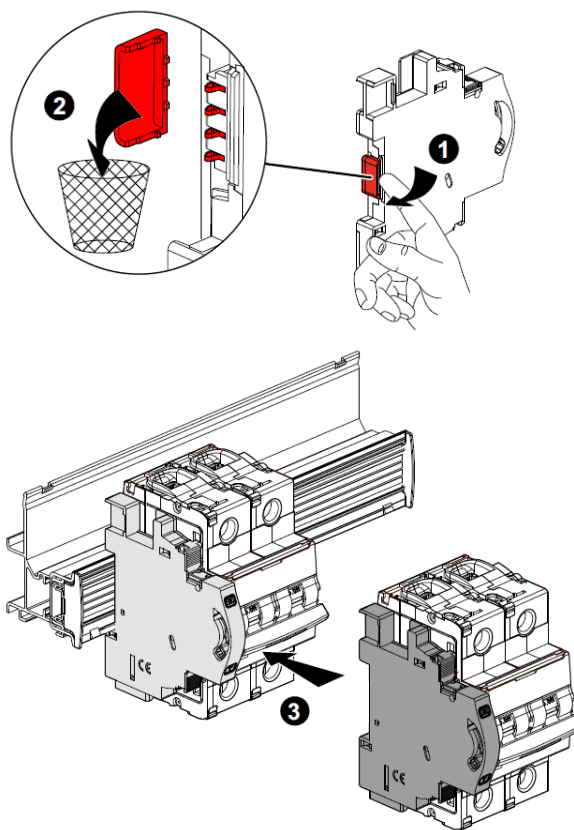
. Via specific communication rails (cat. nos 4 149 01/02/03).



. Allow data transmission between the different EMS CX³ modules.
This type of connection is recommended when there are several EMS CX³ modules on the same DIN row.



Implementing: with this configuration, the plastic protection cover of the backside communication ports on the EMS CX³ module must be removed.



EMS CX³ - Signalling Auxiliary Contact (CA + SD)

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4. PREPARATION –CONNECTION *(continued)*

Data connection (EMS CX³ modules inter-connection)

(continued):*

. Via a mix between specific communication patch cords and communication rails in order to create a link between several rows

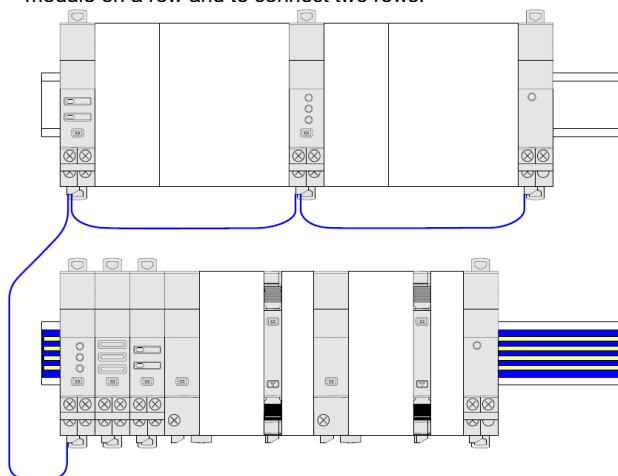
Two situations:

- Individually connected with communication rails.
The communication patch cord allows to connect two rows.



- Individually connected with communication patch cords & communication rail.

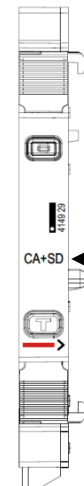
The communication patch cords allow to connect EMS CX³ module on a row and to connect two rows.



5. GENERAL CHARACTERISTICS

Front face marking:

. By permanent ink pad printing (red line) and laser marking

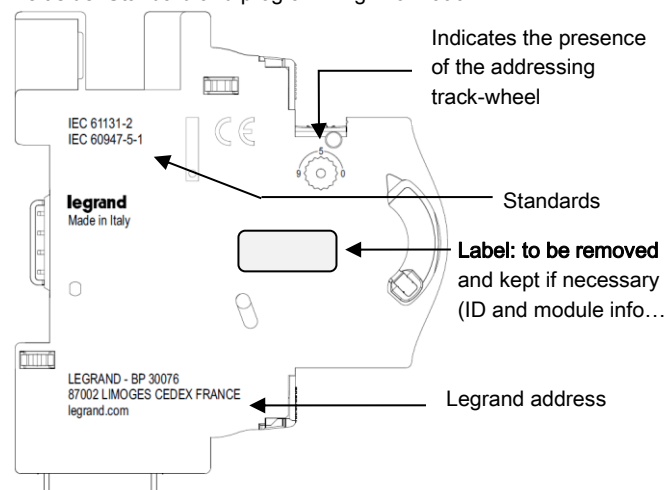


Function name:
CA = auxiliary contact
SD = fault signalling

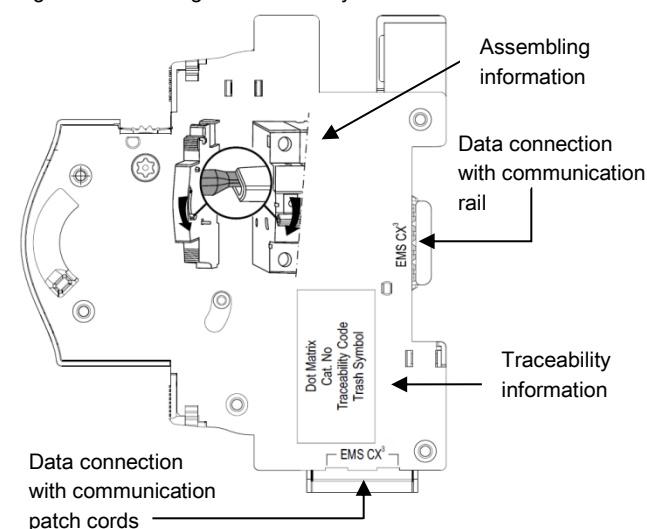
Lateral side marking:

. By laser.

left side: Standard and programming information



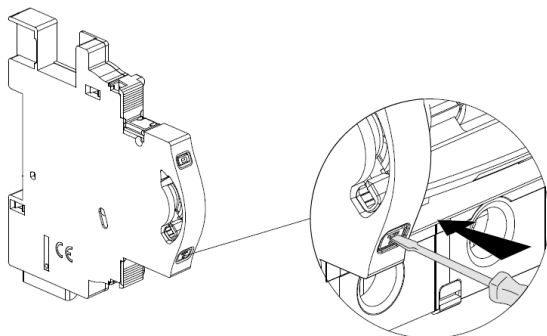
right side: installing and traceability information



5. GENERAL CHARACTERISTICS *(continued)*

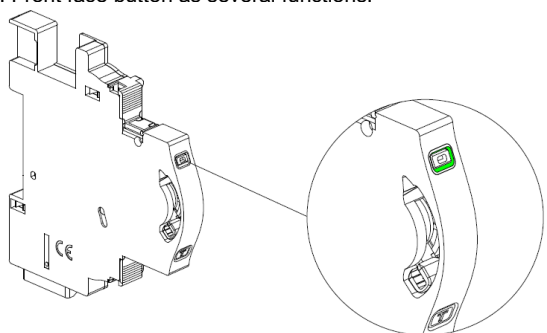
Test button:

- . It allows to check the correct association between the module and the associated device.






Functions button:

- . Front face button as several functions:



- . Give information about the operating state on the module

Possible states:

Led colour	State	Meaning
 red	Slow blinking	Error (e.g. addressing error)
	Fast blinking	No function
	Steady (pressing the multifunction button longer than 20 sec.)	Total reset [any firmware updates are preserved]
 green	Slow blinking	System process is running. Wait until the Led turns steady
	Fast blinking (pressing the multifunction button for 10 sec.)	put in "Stand-by" the EMS CX ³ module (no remote action and communication available)
	Steady	System OK, connection is running
 orange	Slow blinking	Creation of a link with "Link Functionality" procedure (<i>see next §</i>)
	Fast blinking	Device's firmware update in progress
	Steady	No function

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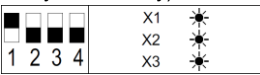
5. GENERAL CHARACTERISTICS *(continued)*

Link Functionality:

. This function allows you to link two EMS CX³ modules to create automatic actions that, once programmed, can run independently without a connection to a manager is needed.

The basic rule is the link between an event (circuit breaker that trip, a threshold exceeded, etc.) and an action accordingly (signalling, opening of a circuit by motorized control or contactor, etc.).

Possible associations are:

Event generator	Action module		
	Command: 4 149 32	State + Command: 4 149 31	State: 4 149 30
Measure: 4 149 19/20/23	✓	✓	<div>✓</div> Only with the module configured (locally or remotely) as shown: 
State: 4 149 29/30	✓	✓	<div>✗</div> Is sufficient to configure the module (locally or remotely) as "Slave"
State + Command: 4 149 31	✓	✓	<div>✗</div> Is sufficient to configure the module (locally or remotely) as "Slave"

Note:

- association can only be of type 1 to 1 (1 event and 1 action).
- modules already associated cannot be used for other associations.
- all the configuring procedure will be done with the Configuration Software (available online for free). *[For more details refer to the Installation Manual of EMS CX³ Configuration software]*

Modules compatible with "Link Functionality" feature: firmware versions and production date:

Cat n°	Firmware version	Production date indicated on the label sticked on the side of the module
4 149 19	ver. ≥ 2.0.1	date ≥ 18W29
4 149 20	ver. ≥ 2.0.1	date ≥ 18W49
4 149 23	ver. ≥ 2.0.1	date ≥ 18W49
4 149 29	ver. ≥ 2.0.1	date ≥ 18W49
4 149 30	ver. ≥ 2.0.2	date ≥ 18W32
4 149 31	ver. ≥ 2.0.6	date ≥ 18W45
4 149 32	ver. ≥ 3.0.2	date ≥ 18W39
4 149 36	ver. ≥ 2.0.4	date ≥ 18W38
4 149 37	ver. ≥ 2.0.4	date ≥ 18W43
4 149 40	ver. ≥ 3.0.8	date ≥ 18W34

5. GENERAL CHARACTERISTICS *(continued)*

Insulation voltage:

. Ui = 400 V

Pollution degree:

. 2 according to IEC/EN 60898-1.

Overvoltage category:

. III

Dielectric strength:

. 2500 V

Tripping force:

. Between 1 and 1,5 Nm.

Mechanical endurance:

. These devices support the mechanical cycles of the associated devices

. 20,000 manoeuvres

Plastic material:

. Self-extinguishing polycarbonate.

. Heat and fire resistant according to IEC/EN 60695-2-12, glow-wire test at 960°C.

. Classification UL 94 / IECEN 60695-11-10: V1

Ambient operating temperature:

. Min. = -25°C. Max. = +70°C

Ambient storage temperature:

. Min. = -40°C. Max. = +70°C

Protection Index:

. Protection index of terminals against direct contacts:

IP2X (IEC/EN 60529).

. Protection index of terminals against solid and liquid bodies (wired device): IP 20 (IEC/EN 60529).

. Protection index of the front face against solid and liquid bodies: IP 40 (IEC/EN 60529).

. Class II, front panel with faceplate.

Average weight per device:

. 0,032 kg.

Volume when packed:

. 0,21 dm³.

Consumption:

. Values at 12 VDC

0,236 W

19,7 mA

6. SYSTEM ARCHITECTURES

The EMS CX³ is a polyvalent system and, according to the needs of the customer, can be set up and/or used as “Stand-alone” or “Supervised” system. Based on this choice the configuration and addressing methods are different.

Four possible architectures are provided:

6.1 Stand-alone system

6.1.1 with local addressing (through the track wheel)

6.1.2 with remote addressing (through a computer)

6.2 Supervised (Computer Supervisory System)

6.2.1 with local addressing

6.2.2 with remote addressing

6.1 Stand-alone system

. **Stand-alone** = autonomous system. To be used by the end-user if it is not necessary to have a computer for the supervision outside the envelope. Everything can be managed on site.

6.1.1 Stand-alone system with local addressing (through the track wheel)

Local addressing advantages:

- No configuration software needed to set-up the installation
- **It is not necessary to use a computer to manage settings** (configurations, test, ...) and to use the system (visualize and be alerted, ...). Everything can be done through the Mini configuration module (local display, cat. no 4 149 36/37). [Refer to the technical sheet dedicated to this module for details].
- No communication Interfaces or gateways are required.
- Installation can be done without the intervention of a System Integrator

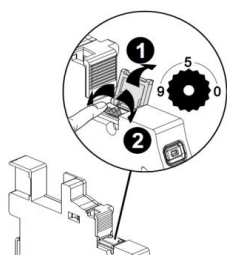
Programming procedure:

. For EMS CX³ modules which need some: mandatory through to lateral DIP-switch of each EMS CX³ modules (see § "Module configuration")

Addressing procedure:

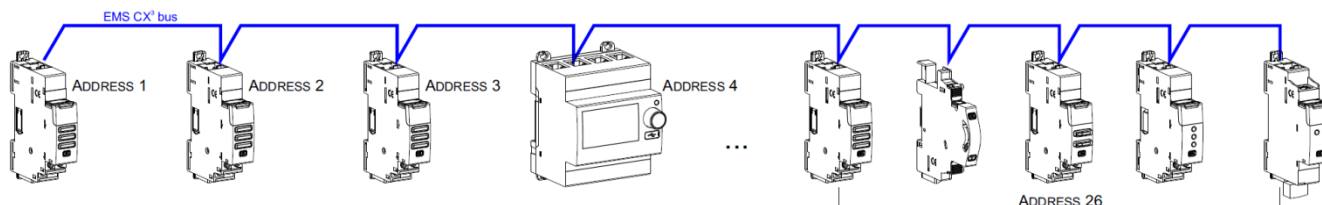
. For all EMS CX³ modules: mandatory through the track wheel located on the top upper face of each EMS CX³ modules

. Marked from 0 to 9 in order to locally define the Modbus address of the EMS CX³ modules



Consequences of the local addressing mode (through the track wheel):

- . Each device of the system must be addressed.
- . Addresses available: from 1 to 9
- . Address 0 not permitted
- . It is possible to assign to several devices the same address with the purpose of grouping different functions, **because they are related to the same electrical circuit**. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ mini configuration module (local display) the grouped function will be displayed as a unique “device” with all grouped functions. [Refer to the schemes hereunder]



Note for the mini configuration module (local display)

- . It is possible to assign it the same address as another EMS CX³ through the programming menu of the device
- . The mini configuration module can be placed everywhere in the EMS CX³ bus

6. SYSTEM ARCHITECTURES

6.1 Stand-alone system *(continued)*

6.1.2 Stand-alone system with remote addressing (through a computer)

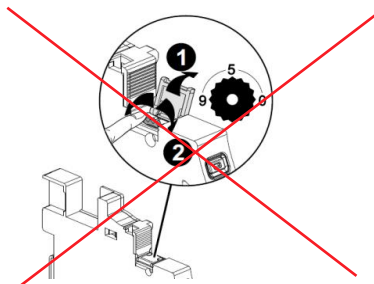
Remote addressing advantages:

- Whole configuration (addresses and functions) can be set up through the EMS Configuration software
- Configuration software available for free
- **Automatic detection of the EMS CX³ modules** installed in the system (characteristics, functions, configuration...)
- **Increased settings possibilities: load shedding function**
- Increased addressing: **up to 30 Modbus addresses in a system**

Programming procedure:

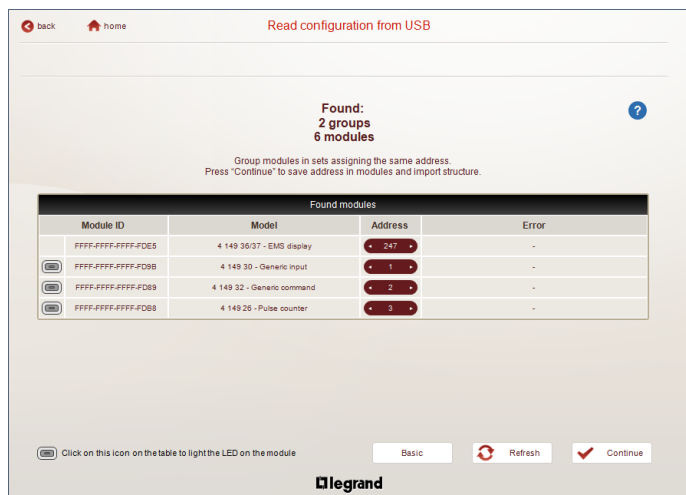
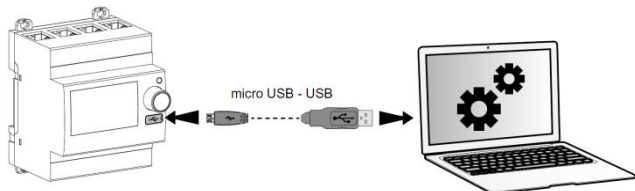
. For EMS CX³ modules which need some: possible through the lateral DIP-switch of each EMS CX³ modules (see § "Module configuration").

Addressing procedure:



- . It is not necessary to address the EMS CX³ modules. The track wheel must be left in default position "0".
- . All the addressing/configuring procedure will be done with the Configuration Software (available online for free)
- . With remote addressing, the software does the automatic detection of modules installed in the system, but the supervision is not possible until the user assigns the remote address and all the characteristics to each module.

Note: it is mandatory to connect the computer to the mini configuration module with an USB-micro USB cable. [For more details, refer to User Manual Document]



6. SYSTEM ARCHITECTURES

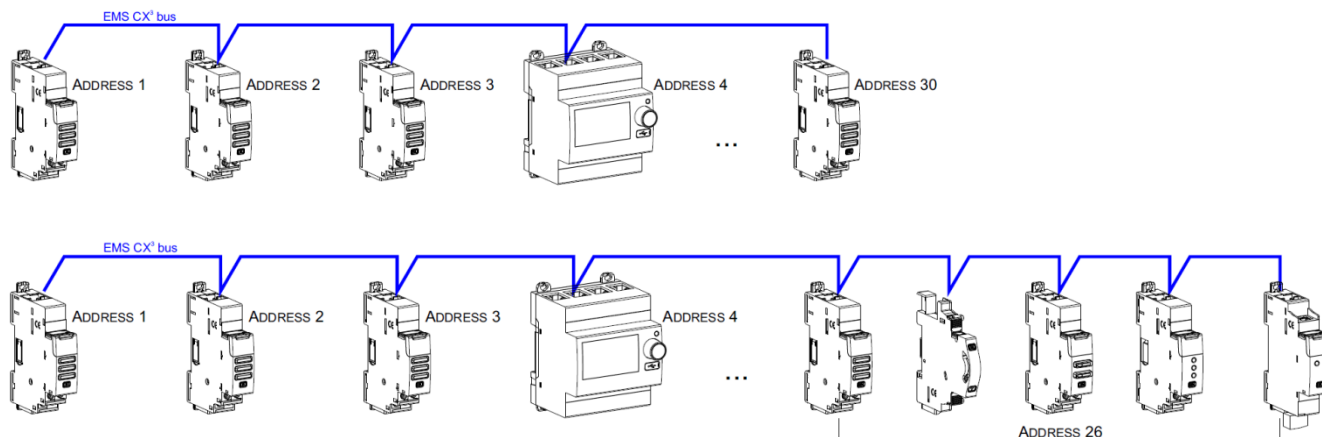
6.1 Stand-alone system *(continued)*

6.1.2 Stand-alone system with remote addressing (through a computer) *(continued)*

Consequences for the system architecture:

- for 1 mini configuration module (cat. no 4 149 36/37)
 - o up to **30 EMS CX³ modules** (eg. 30 devices grouped per functions with addresses from 1 to 30)

It is possible to assign to several devices the same address with the purpose of grouping different functions, **because they are related to the same electrical circuit**. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ display or in a supervision system the grouped function will be displayed as a unique “device” with all grouped functions. *[Refer to the schemes here under]*



Note for the mini configuration module (local display)

- . It is possible to assign it the same address as another EMS CX³
- . The mini configuration module can be placed everywhere in the EMS CX³ bus

6.2 Supervised system (Computer Supervisory System)

. **Supervised system** = System to be used through a Computer Supervisory System to remotely read data from the EMS CX³ devices and/or do operations on these devices (e.g. commands of a motor driven or contactor ...).

6.2.1 Supervised system-with local addressing (through the track wheel)

Local addressing advantages:

- No configuration software needed to set-up the installation
- Installation can be done without the intervention of a System Integrator

Programming procedure:

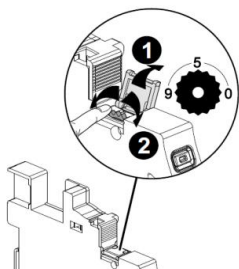
. For EMS CX³ modules which need some: mandatory through to lateral DIP-switch of each EMS CX³ modules (see § “Module configuration”)

Addressing procedure:

. For all EMS CX³ modules: mandatory through the track wheel located on the top upper face of each EMS CX³ modules

. Marked from 0 to 9 in order to locally define the Modbus address to EMS CX³ modules

In this system the Modbus address of an EMS CX³ module device or group of modules (several functions) is obtained considering the address of the interface Modbus/EMS CX³ Interface as tenth and the address of a device or group of function as unit (e.g. Interface address 1 = 10 → address of module n°5 = Modbus address 15)



6. SYSTEM ARCHITECTURES *(continued)*

6.2 Supervised system (Computer Supervisory System) *(continued)*

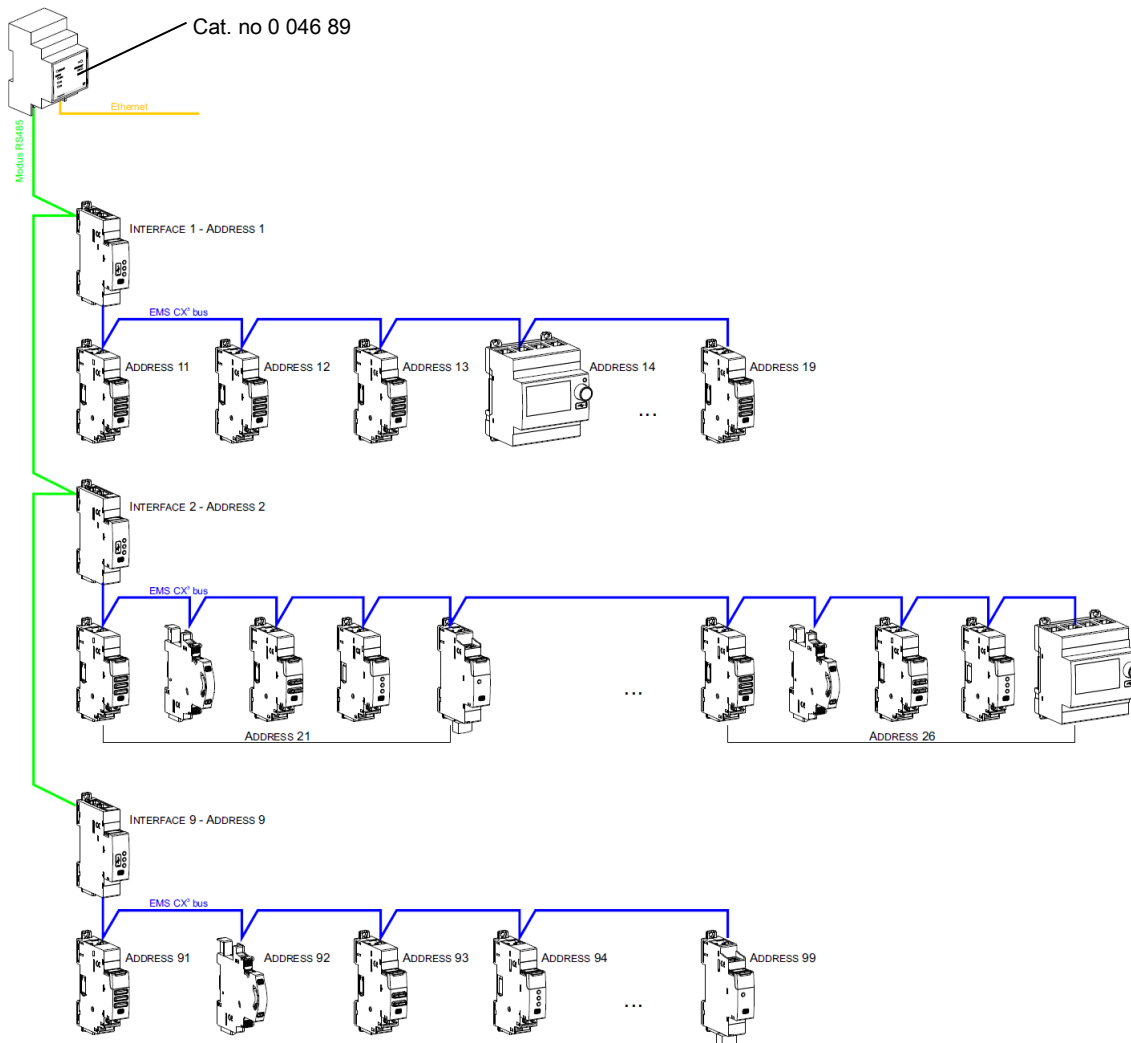
6.2.1 Supervised system-with local addressing (through the track wheel) *(continued)*

Consequences of the local addressing mode (through the track wheel):

- . Each device of the system must be addressed.
- . Addresses available: from 1 to 9
- . Address 0 not permitted

It is possible to assign to several devices the same address with the purpose of grouping different functions, **because they are related to the same electrical circuit**. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ display or in a supervision system the grouped function will be displayed as a unique "device" with all grouped functions. *[Refer to the scheme hereunder]*

Note: In this configuration the Modbus address of an EMS CX³ module device or group of modules (several functions) is obtained considering the address of the interface Modbus/EMS CX³ Interface as tenth and the address of a device or group of function as unit (e.g. Interface address 1 = 10 and device address = 5 → Modbus address = 15)



Consequences for the system architecture:

- for 1 IP/Modbus gateway (cat. no 0 046 89):
 - o up to **81 Modbus address**
 - o mandatory limit of max. **9 Modbus/EMS CX³ interfaces** or max. **1000 m of Modbus cable** (cable Belden 9842, Belden 3106A or equivalent).
- for 1 Modbus/EMS CX³ Interface (cat. no 4 149 40):
 - o up to **30 EMS CX³ modules** (ex. 30 devices grouped per functions with addresses from 1 to 9)

Note: with local addressing, the Modbus/EMS CX³ interface, does the automatic detection of modules (characteristics, functions, configuration...)

6. SYSTEM ARCHITECTURES *(continued)*

6.2 Supervised system (Computer Supervisory System) *(continued)*

6.2.2 Supervised system-with remote addressing (through a computer)

Remote addressing advantages:

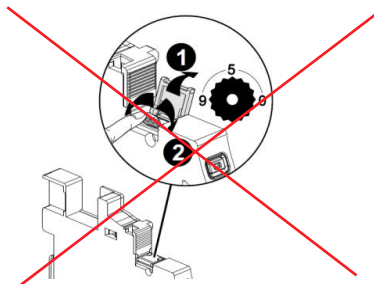
- Whole of configuration (addresses and functions) can be done a remotely through the EMS Configuration software
- Configuration software available for free
- **Automatic detection of the EMS CX³ modules** installed in the system (characteristics, functions, configuration...)
- **Increased settings possibilities: load shedding function**
- Increased addressing: **up to 32 Modbus/EMS CX³ interfaces**
- Increased addressing: **up to 247 Modbus addresses in a system**

Programming procedure:

. For EMS CX³ modules which need some: possible through the lateral DIP-switch of each EMS CX³ modules (see § "Module configuration").

Note: via the configuration software it is possible to assign all the functions and characteristics of each EMS CX³ module

Addressing procedure:

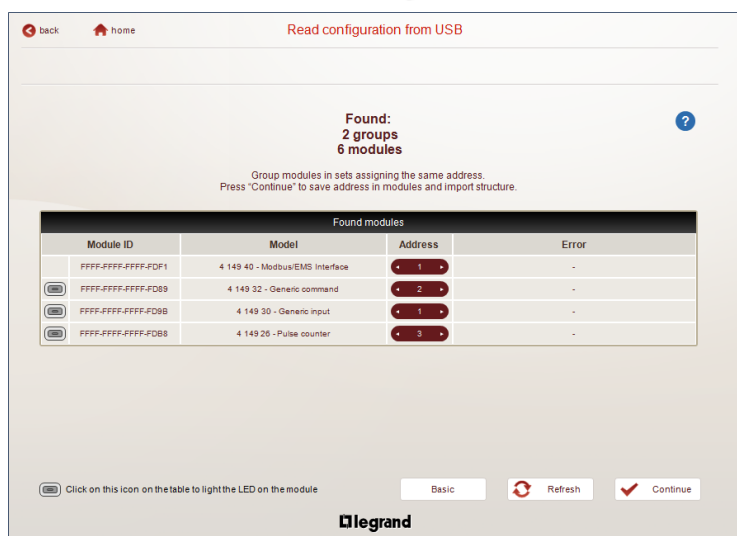
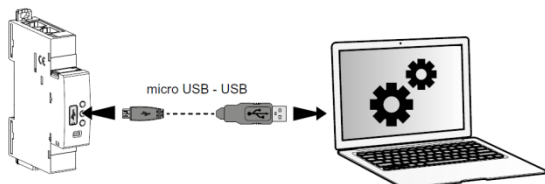


. It is not necessary to address the EMS CX³ modules. The track wheel must be left in default position "0".

. All the addressing/configuring procedure will be done with the Configuration Software (available online for free)

. With remote addressing, the software does the automatic detection of modules installed in the system, but the supervision is not possible until the user assigns the remote address and all the characteristics to each module.

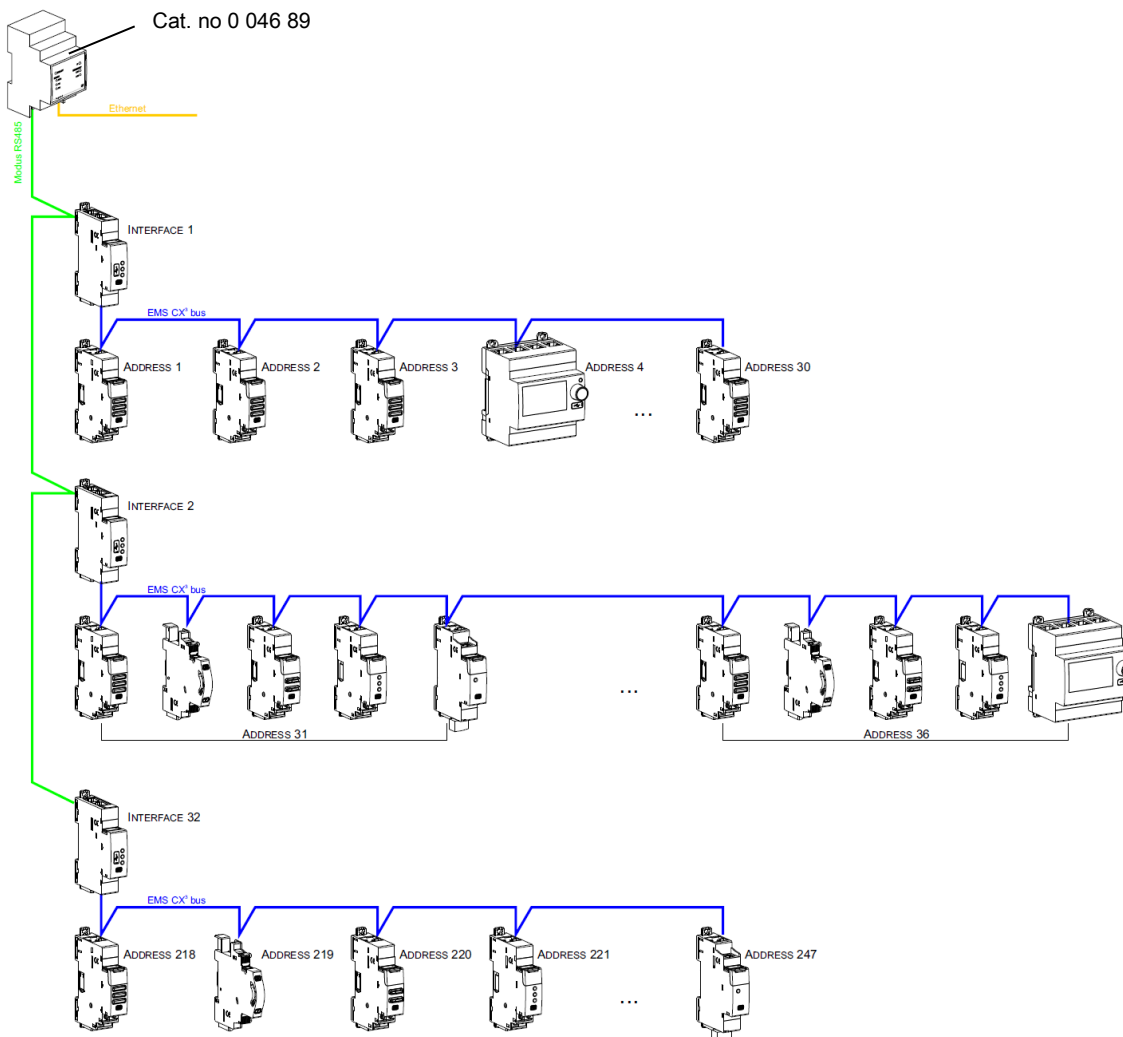
Note: it is mandatory to connect the computer to the different Modbus/EMS CX³ interface with an USB-micro USB cable (one interface at a time). [For more details, refer to the User Manual Document]



6. SYSTEM ARCHITECTURES *(continued)*

6.2 Supervised system (Computer Supervisory System) *(continued)*

6.2.2 Supervised system-with remote addressing (through a computer) *(continued)*



Consequences for the system architecture:

- for 1 IP/Modbus gateway (cat. no 0 046 89):
 - o up to **247 Modbus address**
 - o Because of Modbus: mandatory limit of max. **32 Modbus/EMS CX³ interfaces** or max. **1000 m of Modbus cable** (cable Belden 9842, Belden 3106A or equivalent).
- for 1 Modbus/EMS CX³ Interface (cat. no 4 149 40):
 - o up to **30 EMS CX³ modules or grouped modules** (e.g. 30 devices grouped per functions with addresses from 1 to 30)

It is possible to assign to several devices the same address with the purpose of grouping different functions, **because they are related to the same electrical circuit**. For example, it is possible to assign the same address to a signalling auxiliary module (cat. no 4 149 29), a universal control module (cat. no 4 149 32), a measuring module, and so on. In this way on the EMS CX³ display or in a supervision system the grouped function will be displayed as a unique "device" with all grouped functions. *[Refer to the scheme up here]*

7. COMPLIANCE AND APPROVALS

Compliance to standards:

- . Compliance with Directive on electromagnetic compatibility (EMC) n° 2014/30/EU
- . Compliance with low voltage directive n° 2014/35/EU.
- . Electromagnetic Compatibility:
 - IEC/EN 61131-2
 - IEC/EN 60947-5-1

Environment respect - Compliance with EU directives:

- . Compliance with Directive 2011/65/EU as amended by Directive 2015/863 (RoHS 2) on the restriction of the use of certain hazardous substances in electrical and electronic equipment.
- . Compliance with REACH regulation (1907/2006): at the date of the publication of this document no element of the SVHC substance list (updated on 27/06/2018) is present in these products.
- . WEEE directive (2012/19/EU): the sale of this product is subject to a contribution to eco-organisations in each country responsible for managing end-of-life products in the field of application of the European Waste Electronic and Electrical Equipment Directive.

Plastic materials:

- . Halogens-free plastic materials.
- . Marking of parts according to ISO 11469 and ISO 1043.

Packaging:

- . Design and manufacture of packaging compliant to decree 98-638 of the 20/07/98 and also to directive 94/62/CE.

Environmental profile:

- . PEP document available

Installation software:

- . XL PRO³.